# Data Structures and Algorithm 

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## MULTIPOP



## Analysis of MULTIPOP

A sequence of $n$ PUSH, POP, and MULTIPOP operations on an initially empty stack.

- The worst-case cost of a MULTIPOP operation is $O(n)$
- The worst-case time of any stack operation is therefore $O(n)$
- A sequence of $n$ operations costs is $O\left(n^{2}\right)$


## This bound is not tight!

## Amortized analysis

$\square$ An amortized analysis is any strategy for analyzing a sequence of operations to show that the average cost per operation is small, even though a single operation within the sequence might be expensive.

- Even though we're taking averages, however, probability is not involved!
$\square$ An amortized analysis guarantees the average performance of each operation in the worst case.


## Types of amortized analyses

Three common amortization arguments:

- Aggregate method
- Accounting method
- Potential method

The aggregate method, though simple, lacks the precision of the other two methods. In particular, the accounting and potential methods allow a specific amortized cost to be allocated to each operation.

## Aggregate analysis

- We show that for all $n$, a sequence of $n$ operation takes worst-case time $T(n)$ in total.
- Hence, the average cost, or amortized cost, per operation is $T(n) / n$


## MULTIPOP (aggregate method)

- Each object can be popped at most once for each time it is pushed. Therefore, the number of times that POP can be called on a nonempty stack, including calls within MULTIPOP, is at most the number of PUSH operations, which is at most $n$.
- Any sequence of $n$ PUSH, POP, and MULTIPOP operations takes a total of $O(n)$ time. The average cost of an operation is $T(n) / n=O(1)$


## 8-bit binary counter

| Counter Value |  |  | ¢ | 人 |  |  | Total cost |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 00 | 00 | 00 | 0 | 0 | 0 |
| 1 | 0 | 00 | 00 | 00 | 0 | 1 | 1 |
| 2 | 0 | 00 | 00 | 00 | 1 | 0 | 3 |
| 3 | 0 | 00 | 00 | 00 | 1 |  | 4 |
| 4 | 0 | 00 | 00 | 01 | 0 | 0 | 7 |
| 5 | 0 | 00 | 00 | 01 | 0 | 1 | 8 |
| 6 | 0 | 00 | 00 | 01 | 1 |  | 10 |
| 7 | 0 | 00 | 00 | 01 | 1 |  | 11 |
| 8 | 0 | 00 | 00 | 10 | 0 | 0 | 15 |

## Incrementing a binary counter

An array $A[0 \ldots k-1]$ of bit, where length $[A]=k$, as the counter.

$$
x=\sum_{i=0}^{k-1} A[i] \cdot 2^{i}
$$

INCREMENT(A)

1. $i \leftarrow 0$
2. while $i<$ length $[A]$ and $A[i]=1$
3. $\quad$ do $A[i] \leftarrow 0$
4. $i=i+1$
5. if $i<$ length $[A]$
6. then $A[i] \leftarrow 1$

## Binary counter (aggregate method)

For $i=0,1 \ldots,\lfloor\lg n\rfloor$, bit $A[i]$ flips $\left\lfloor n / 2^{i}\right\rfloor$ times in a sequence of $n$ INCREMENT operation on an initially zero counter.

The total number of flips in the sequence is thus

$$
\begin{aligned}
\sum_{i=0}^{\lfloor\lg n\rfloor}\left\lfloor\frac{n}{2^{i}}\right\rfloor & <n \sum_{i=0}^{\infty} \frac{1}{2^{i}} \\
& =2 n \\
& =O(n)
\end{aligned}
$$

The amortized cost per operation is

$$
O(n) / n=O(1)
$$

## MULTIPOP (accounting method)



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## MULTIPOP (accounting method)



## MULTIPOP (accounting method)



## Accounting method

$\square$ We assign differing charges to different operations, with some operations charged more or less than they actually cost.
$\square$ The amount we charge an operation is called its amortized cost.
$\square$ When an operation's amortized cost exceeds its actual cost, the difference is assigned to specific objects in the data structure as credit.

## Accounting method

- We denote the actual cost of the $i$ th operation by $c_{i}$ and the amortized cost of the $i$ th operation by $c_{i}$, we require

$$
\sum_{i=1}^{n} \hat{c}_{i} \geq \sum_{i=1}^{n} c_{i}
$$

Why?

## Binary counter (accounting method)

## Amortized costs

| Set a bit to 1 | 2, |
| :--- | :--- |
| Flip the bit back to 0 | 0. |

## Potential method

- For each $i=1,2, \ldots, n$, we let $c_{i}$ be the actual cost of the $i$ th operation and $D_{i}$ be the data structure that results after applying the $i$ th operation to data structure $D_{i-1}$.
- A potential function $\Phi$ maps each data structure $D_{i}$ to a real number $\Phi\left(D_{i}\right)$, which is the potential associated with data structure $D_{i}$.
- A amortized cost $\hat{c}_{i}$ of $i$ th operation with respect to potential function is $\Phi$ defined by

$$
\widehat{c}_{i}=c_{i}+\Phi\left(D_{i}\right)-\Phi\left(D_{i-1}\right) .
$$

## Potential method

- The total amortized cost of the $n$ operation is

$$
\begin{aligned}
\sum_{i=1}^{n} \hat{c}_{i} & =\sum_{i=1}^{n}\left(c_{i}+\Phi\left(D_{i}\right)-\Phi\left(D_{i-1}\right)\right) \\
& =\sum_{i=1}^{n} c_{i}+\Phi\left(D_{n}\right)-\Phi\left(D_{0}\right)
\end{aligned}
$$

- Define a potential function $\Phi$ so that $\Phi\left(D_{n}\right) \geq \Phi\left(D_{0}\right)$, then the total amortized cost $\sum_{i=1}^{n} \hat{c}_{i}$ is an upper bound on the total actual $\operatorname{cost} \sum_{i=1}^{n} c_{i}$.


## MULTIPOP (potential method)

We define the potential function $\Phi$ on a stack to be the number of objects in the stack.

- PUSH operation

$$
\begin{aligned}
& \Phi\left(D_{i}\right)-\Phi\left(D_{i-1}\right)=(s+1)-s=1 \\
& \widehat{c_{i}}=c_{i}+\Phi\left(D_{i}\right)-\Phi\left(D_{i-1}\right)=1+1=2
\end{aligned}
$$

- MULTIPOP $(S, k)$ operation and $k^{\prime}=\min (k, s)$

$$
\begin{aligned}
& \Phi\left(D_{i}\right)-\Phi\left(D_{i-1}\right)=-k^{\prime} \\
& \hat{c}_{i}=c_{i}+\Phi\left(D_{i}\right)-\Phi\left(D_{i-1}\right)=k-k^{\prime}=0
\end{aligned}
$$

- POP operation and $k^{\prime}=\min (1, s)$

$$
\begin{aligned}
& \Phi\left(D_{i}\right)-\Phi\left(D_{i-1}\right)=-k^{\prime} \\
& \widehat{c}_{i}=c_{i}+\Phi\left(D_{i}\right)-\Phi\left(D_{i-1}\right)=k-k^{\prime}=0
\end{aligned}
$$

## Binary counter (potential method)

- We define the potential of counter after the $i$ th INCREMENT operation to be $b_{i}$, the number of 1's in the counter after the $i$ th operation.
- Suppose that the $i$ th INCREMENT operation reset $t_{i}$ bit.

$$
\begin{aligned}
& \Phi\left(D_{i}\right)-\Phi\left(D_{i-1}\right)=\left(b_{i-1}-t_{i}+1\right)-b_{i-1} \\
& =1-t_{i} \\
& \widehat{c_{i}}=c_{i}+\Phi\left(D_{i}\right)-\Phi\left(D_{i-1}\right) \\
& \quad=\left(t_{i}+1\right)+\left(1-t_{i}\right) \\
& \quad=2
\end{aligned}
$$

## 8-bit binary counter

Counter
Value

| $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $\mathbf{1}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{1}$ | $\mathbf{1}$ | $\Phi\left(D_{i}\right)-\Phi\left(D_{i-1}\right)$ |
| $\mathbf{2}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{1}$ | $\mathbf{0}$ | $\mathbf{3}$ | $=\left(b_{i-1}-t_{i}+1\right)-b_{i-1}$ |
| $\mathbf{3}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{1}$ | $\mathbf{1}$ | $\mathbf{4}$ | $=(2-1+1)-2$ |
| $\mathbf{4}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{1}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{7}$ | $=0$ |
| $\mathbf{5}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{1}$ | $\mathbf{0}$ | $\mathbf{1}$ |  |  |
| $\mathbf{6}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{1}$ | $\mathbf{1}$ | $\mathbf{0}$ | $\mathbf{8}$ | $\hat{c}_{i}=c_{i}+\Phi\left(D_{i}\right)-\Phi\left(D_{i-1}\right)$ |
| $\mathbf{7}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{1}$ | $\mathbf{1}$ | $\mathbf{1}$ | $\mathbf{1 1}$ | $=2+0$ |
| $\mathbf{8}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{1}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{0}$ | $\mathbf{1 5}$ |  |

## 8-bit binary counter

Counter
Value
$\left.\begin{array}{lllllllllll}0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 2 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 \\ 3 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 1 \\ 4 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 \\ 5 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 1 \\ 6 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 0 \\ 7 & 0 & 0 & 0 & 0 & 0 & 1 & 1 & 1 \\ 8 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0\end{array}\right)$

Total
cost
0
$1 \quad \Phi\left(D_{i}\right)-\Phi\left(D_{i-1}\right)$
$3=\left(b_{i-1}-t_{i}+1\right)-b_{i-1}$
$4=(3-3+1)-3$
$7=-2$
$8 \hat{c}_{i}=c_{i}+\Phi\left(D_{i}\right)-\Phi\left(D_{i-1}\right)$
$10=4-2$
$11=2$
15

Binary counter (potential method)

$$
\begin{aligned}
\sum_{i=1}^{n} \widehat{c_{i}} & =\sum_{i=1}^{n} c_{i}+\Phi\left(D_{n}\right)-\Phi\left(D_{0}\right) \\
\sum_{i=1}^{n} c_{i} & =\sum_{i=1}^{n} \widehat{c_{i}}-\Phi\left(D_{n}\right)+\Phi\left(D_{0}\right) \\
& =\sum_{i=1}^{n} 2-b_{n}+b_{0} \\
& =2 n-b_{n}+b_{0} \\
& =O(n)
\end{aligned}
$$

## Hash tables by chaining

Expected time to search for a record with a given key


Expected search time $=\Theta(1)$ if $\alpha=O(1)$, or equivalently, if $n=O(m)$.
$\alpha=n / m=$ average number of keys per slot.

## Hash tables by open-addressed

Theorem. Given an open-addressed hash table with load factor $\alpha=n / m<1$, the expected number of probes in an unsuccessful search is at most $1 /(1-\alpha)$.

Theorem. Given an open-addressed hash table with load factor $\alpha=n / m<1$, the expected number of probes in an successful search is at most

$$
\frac{1}{\alpha} \ln \frac{1}{1-\alpha}
$$

## How large should a hash table be?

Goal: Make the table as small as possible, but large enough so that it won't overflow (or otherwise become inefficient).
Problem: What if we don't know the proper size in advance?
Solution: Dynamic tables.
IDEA: Whenever the table overflows, "grow" it by allocating a new, larger table. Move all items from the old table into the new one, and free the storage for the old table.

## Example of a dynamic table

1. INSERT

## Example of a dynamic table (cont.)

1. INSERT
2. INSERT


## Example of a dynamic table (cont.)

1. INSERT
2. INSERT


## Example of a dynamic table (cont.)

\author{

1. INSERT <br> 2. INSERT
}


## Example of a dynamic table (cont.)

1. INSERT
2. INSERT
3. INSERT


## Example of a dynamic table (cont.)

1. INSERT
2. INSERT
3. INSERT


## Example of a dynamic table (cont.)

1. INSERT
2. INSERT
3. INSERT


## Example of a dynamic table (cont.)

1. INSERT
2. INSERT
3. INSERT
4. INSERT


## Example of a dynamic table (cont.)

1. INSERT
2. INSERT
3. INSERT
4. INSERT
5. INSERT


## Example of a dynamic table (cont.)

1. INSERT
2. INSERT
3. INSERT
4. INSERT
5. INSERT


## Example of a dynamic table (cont.)

1. INSERT
2. INSERT
3. INSERT
4. INSERT
5. INSERT


## Example of a dynamic table (cont.)

1. INSERT
2. INSERT
3. INSERT
4. INSERT
5. INSERT
6. INSERT
7. INSERT


## Worst-case analysis

Consider a sequence of $n$ insertions. The worst-case time to execute one insertion is $\Theta(n)$. Therefore, the worst-case time for $n$ insertions is $n \cdot \Theta(n)=\Theta\left(n^{2}\right)$.

This bound is not tight! In fact, the worst-case cost for $n$ insertions is only $\Theta(n)$.

## Let's see why.

## Tighter analysis

Let $c_{i}=$ the cost of the $i$ th insertion
$= \begin{cases}i & \text { if } i-1 \text { is an exact power of } 2, \\ 1 & \text { otherwise } .\end{cases}$

| $i$ | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 |
| ---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\operatorname{size}_{i}$ | 1 | 2 | 4 | 4 | 8 | 8 | 8 | 8 | 16 | 16 |
| $c_{i}$ | 1 | 2 | 3 | 1 | 5 | 1 | 1 | 1 | 9 | 1 |
|  |  |  |  |  |  |  |  |  |  |  |

## Tighter analysis (cont.)

Let $c_{i}=$ the cost of the $i$ th insertion
$= \begin{cases}i & \text { if } i-1 \text { is an exact power of } 2, \\ 1 & \text { otherwise } .\end{cases}$

| $i$ | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 |
| ---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| size $_{i}$ | 1 | 2 | 4 | 4 | 8 | 8 | 8 | 8 | 16 | 16 |
| $c_{i}$ | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
|  |  | 1 | 2 |  | 4 |  |  |  | 8 |  |

## Tighter analysis (aggregate method)

The total cost of $n$ TABLE-INSERT operations is therefore

$$
\begin{aligned}
\sum_{i=1}^{n} c_{i} & \leq n+\sum_{j=0}^{\lfloor\lg n\rfloor} 2^{j} \\
& \leq n+2 n \\
& =3 n \\
& =\Theta(n)
\end{aligned}
$$

Thus, the average cost of each dynamic-table operation is $\Theta(n) / n=\Theta(1)$.

## Accounting analysis of dynamic tables

Charge an amortized cost of $\widehat{c_{i}}=\$ 3$ for the $i$ ith insertion.

- $\$ 1$ pays for the immediate insertion.
- $\$ 2$ is stored for later table doubling.

When the table doubles, $\$ 1$ pays to move a recent item, and $\$ 1$ pays to move an old item.

## Accounting analysis of dynamic tables

1. INSERT
2. INSERT
3. INSERT
4. INSERT
5. INSERT


## Accounting analysis of dynamic tables

1. INSERT
2. INSERT
3. INSERT
4. INSERT
5. INSERT


## Accounting analysis of dynamic tables

1. INSERT
2. INSERT
3. INSERT
4. INSERT
5. INSERT


## Accounting analysis of dynamic tables

1. INSERT
2. INSERT
3. INSERT
4. INSERT
5. INSERT
6. INSERT
7. INSERT

| $\$ 0$ |
| :--- |
| $\$ 0$ |
| $\$ 0$ |
| $\$ 0$ |
| $\$ 2$ |
| $\$ 2$ |
| $\$ 2$ |
|  |

## Dynamic table (potential method)

We start by defining a potential function $\Phi$ that is 0 immediately after an expansion but builds to the table size by the time the table is full. The function

$$
\Phi(T)=2 \cdot \operatorname{num}[T]-\operatorname{size}[T]
$$

- num $_{i}$ denote the number of items stored in the table after the $i$ th operation
- size $_{i}$ denote the total size of the table after the $i$ th operation
- $\Phi_{i}$ denote the potential after the $i$ th operation


## Dynamic table (potential method)

- If the $i$ th TABLE-INSERT operation does not trigger an expansion, the amortized cost is

$$
\begin{aligned}
\widehat{c}_{i} & =c_{i}+\Phi_{i}-\Phi_{i-1} \\
& =1+\left(2 \cdot \text { num }_{i}-\text { size }_{i}\right)-\left(2 \cdot \text { num }_{i-1}-\text { size }_{i-1}\right) \\
& =1+\left(2 \cdot \text { num }_{i}-\text { size }_{i}\right)-\left(2 \cdot\left(\text { num }_{i}-1\right)-\text { size }_{i}\right) \\
& =3
\end{aligned}
$$

- If the $i$ th TABLE-INSERT operation triggers an expansion, the amortized cost is

$$
\begin{aligned}
\widehat{c}_{i} & =c_{i}+\Phi_{i}-\Phi_{i-1} \\
& =\text { num }_{i}+\left(2 \cdot \text { num }_{i}-\text { size }_{i}\right)-\left(2 \cdot \text { num }_{i-1}-\text { size }_{i-1}\right) \\
& =\text { num }_{i}+\left(2 \cdot \text { num }_{i}-2 \cdot\left(\text { num }_{i}-1\right)\right)-\left(2 \cdot\left(\text { num }_{i}-1\right)-\left(\text { num }_{i}-1\right)\right) \\
& =3
\end{aligned}
$$

## Table expansion and contraction

Table contraction is analogous to table expansion: when the number of items in the table drops too low, we allocate a new, smaller table and then copy the items form the old table into the new one.

A natural strategy for expansion and contraction is to double the table size when an item is inserted into a full table and halve the size when a deletion would cause the table to become less than half full.

> This strategy cause the amortized cost of an operation to be quite large.

## Problem of natural strategy

We perform the following sequence. I, D, D, I, I, D, D, I, I, ...


Contraction
INSERT DELETE DELETE INSERT
INSERT DELETE

## Improved strategy

- Double the table size when an item is inserted into a full table
- Halve the table size when a deletion causes the table to become less than $1 / 4$ full
- Potential function

$$
\Phi(T)= \begin{cases}2 \cdot \operatorname{num}[T]-\operatorname{size}[T] & \text { if } \alpha(T) \geq 1 / 2 \\ \operatorname{size}[T] / 2-\operatorname{num}[T] & \text { if } \alpha(T)<1 / 2\end{cases}
$$

# Any question? 

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